

Numerical Methods for CSE

The Gram-Schmidt Orthogonalisation

(Explanation of Exercise 1.2)

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In this document I will guide you through the implementation of the Gram-Schmidt orthogonalisation of an ordered finite set $\{\mathbf{a}^1, \dots, \mathbf{a}^k\}$, $k \in \mathbb{N}$, $\mathbf{a}^l \in \mathbb{K}^n$ as explained in the solution code for exercise 1.2. The implementations shown in this document are based on the Gram-Schmidt algorithm shown in (1.5.1) of [1].

Notation

Throughout this document (and my material for the exercise sessions in general) I will be using the following notation in mathematical formulas:

- \mathbf{x} : Column vector (small letter, bold)
- \mathbf{x}^T : Row vector (small letter, bold, transposed)
- \mathbf{A} : Matrix (large letter, bold)

Version 1: Implementation Using Two `for`-Loops

The algorithm presented in (1.5.1) of [1] can be directly implemented using two nested `for`-loops; the implementation may look as follows:

```
for (int j = 1; j < A.cols(); ++j)
{
    for (int l = 0; l < j; ++l)
    {
        Q.col(j) -= A.col(j).dot(Q.col(l)) * Q.col(l)
        ↪ );
    }
}
```

```

    }
    ...
}

```

Version 2: Implementation Using Only One `for`-Loop

In this section I am going to explain the implementation and the mathematical idea behind the solution provided in `/NumCSE/Assignments/Codes`
`↪ /MatVec/GramSchmidt/solutions_nolabels/gramschmidt.cpp`.

In the solution code one can see that the inner-most `for`-loop has been replaced by a matrix-vector multiplication:

```

for (int j = 1; j < A.cols(); ++j)
{
    Q.col(j) -= Q.leftCols(j) * (Q.leftCols(j).
        ↪ transpose() * A.col(j));
}

```

Assuming that the vector indices in mathematical formulas (not in the code) start at 1, i.e., \mathbf{q}^1 being the first vector, then the equation shown in the above code listing can be written as

$$\mathbf{q}^j = \mathbf{q}^j - \mathbf{Q}_{j-1} (\mathbf{Q}_{j-1}^T \mathbf{a}^j) \quad , \quad (1)$$

where \mathbf{Q}_{j-1} is the matrix containing the first $j - 1$ columns of \mathbf{Q} , i.e.,

$$\mathbf{Q}_{j-1} = (\mathbf{q}^1, \dots, \mathbf{q}^{j-1}) \quad . \quad (2)$$

First Confusing Fact: The Indices

The first thing that may be confusing in Eq. 1 is the fact that in the code both the `Q.col(j)` and `Q.leftCols(j)` functions use the same index j , but in the equation shown in Eq. 1 \mathbf{q}^j and \mathbf{Q}_{j-1} use different values for the indices, namely j and $j - 1$ respectively.

The reason for this is the following: since the columns of the matrix $\mathbf{Q} \in \mathbb{R}^{n \times n}$ are numbered from $0, \dots, n - 1$ in the code (not in the mathematical formula), i.e., `Q.col(0)` is the first column (in mathematical notation this would be the vector \mathbf{q}^1), by starting with $j = 1$ in the `for`-loop we are accessing the *second* column of \mathbf{Q} (since `Q.col(0)` is the first column). Further, since `Q.leftCols(j)` selects the first j columns of the matrix \mathbf{Q} (see the [Eigen documentation](#)), for $j = 1$ we are actually selecting only the first column of \mathbf{Q} . Since in each step j of the Gram-Schmidt algorithm the vector \mathbf{q}^j is constructed from the previous $j - 1$ vectors, one can see why we are working with $\mathbf{Q}_{j-1} = (\mathbf{q}^1, \dots, \mathbf{q}^{j-1})$.

Second Confusing Fact: The Equation in General

The second confusing thing in Eq. 1 may be the equation in general.

Why can we replace the inner-most loop by introducing the matrix-vector multiplication shown in Eq. 1?

Working with Projections

The projection operator is defined as [2]

$$\text{proj}_{\mathbf{u}} = \frac{\langle \mathbf{v}, \mathbf{u} \rangle}{\langle \mathbf{u}, \mathbf{u} \rangle} \mathbf{u} = \frac{\mathbf{v} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u} = \frac{\mathbf{v}^T \mathbf{u}}{\mathbf{u}^T \mathbf{u}} \mathbf{u} \quad (3)$$

and it projects the vector \mathbf{v} orthogonally onto the line spanned by vector \mathbf{u} .

If \mathbf{u} is normalized, i.e. $\langle \mathbf{u}, \mathbf{u} \rangle = 1$, then the projection operator simplifies to

$$\text{proj}_{\mathbf{u}} = \mathbf{v} \cdot \mathbf{u} \mathbf{u} = (\mathbf{v}^T \mathbf{u}) \mathbf{u} \quad (4)$$

The main part of the Gram-Schmidt algorithm in (1.5.1) of [1] is given by

```

for j = 2, 3, ..., n do
  qj := aj
  for l = 1, 2, ..., j - 1 do
    qj ← qj - aj · ql ql
  if (qj = 0) then STOP
  else qj ← qj / ||qj||2

```

If we omit the inner-most `for`-loop and write the equation for \mathbf{q}^j in an explicit way, we get

$$\mathbf{q}^j \leftarrow \mathbf{q}^j - \left(\mathbf{a}^j \cdot \mathbf{q}^1 \mathbf{q}^1 + \mathbf{a}^j \cdot \mathbf{q}^2 \mathbf{q}^2 + \dots + \mathbf{a}^j \cdot \mathbf{q}^{j-1} \mathbf{q}^{j-1} \right) \quad (5)$$

Since the resulting vector \mathbf{q}^j gets normalized in a final step, i.e. $\mathbf{q}^j / \|\mathbf{q}^j\|$, we actually have an orthonormalization algorithm. Thus, by using the fact that all previous $\mathbf{q}_1, \dots, \mathbf{q}_{j-1}$ are orthonormalized (orthogonalized and normalized) in Eq. 5 and by using the definition of the projection in Eq. 4, the calculation of \mathbf{q}^j in Eq. 5 can be rewritten as

$$\mathbf{q}^j \leftarrow \mathbf{q}^j - \sum_{l=1}^{j-1} \text{proj}_{\mathbf{q}^l}(\mathbf{a}^j) \quad (6)$$

Corollary 7.5 from [3] defines the orthogonal projection \mathbf{P}_Q to be the projection onto the column-space of the matrix $\mathbf{Q} = (\mathbf{q}_1, \dots, \mathbf{q}_n)$ with orthonormal columns and it is given by

$$\mathbf{P}_Q := \mathbf{Q}\mathbf{Q}^T. \quad (7)$$

This corollary also defines that

$$\mathbf{P}_Q \mathbf{y} = \mathbf{Q}\mathbf{Q}^T \mathbf{y} = \sum_{j=1}^n \mathbf{q}_j \mathbf{q}_j^T \cdot \mathbf{y} \quad (8)$$

Using the definition of the projection operator from Eq. 4 we can now see that

$$\mathbf{P}_Q \mathbf{y} = \sum_{j=1}^n \text{proj}_{\mathbf{q}_j} \mathbf{y} \quad (9)$$

Thus, using the definition of the orthogonal projection \mathbf{P}_Q from Eq. 7 in the calculation of \mathbf{q}^j shown in Eq. 6, we can rewrite Eq. 6 as follows:

$$\begin{aligned} \mathbf{q}^j &\leftarrow \mathbf{q}^j - \sum_{l=1}^{j-1} \text{proj}_{\mathbf{q}^l}(\mathbf{a}^j) \\ &\iff \\ \mathbf{q}^j &\leftarrow \mathbf{q}^j - \underbrace{\mathbf{Q}_{j-1} \mathbf{Q}_{j-1}^T}_{=: \mathbf{P}_{Q_{j-1}}} \mathbf{a}^j, \end{aligned} \quad (10)$$

where \mathbf{Q}_{j-1} is defined in Eq. 2.

The final version of the Gram-Schmidt algorithm — which is also implemented in the solution code — is then given by

```

for j = 2, 3, ..., n do
     $\mathbf{q}^j := \mathbf{a}^j$ 
     $\mathbf{q}^j \leftarrow \mathbf{q}^j - \mathbf{Q}_{j-1} \mathbf{Q}_{j-1}^T \mathbf{a}^j$ 
    if ( $\mathbf{q}^j = \mathbf{0}$ ) then STOP
    else  $\mathbf{q}^j \leftarrow \mathbf{q}^j / \|\mathbf{q}^j\|_2$ 

```

References

- [1] R. Hiptmair, “Numerical methods for computational science and engineering.” <https://www.sam.math.ethz.ch/~grsam/HS16/NumCSE/NumCSE16.pdf>, 2016.

- [2] E. W. Weisstein, "Projection. From MathWorld—A Wolfram Web Resource." <http://mathworld.wolfram.com/Projection.html>.
- [3] M. H. Gutknecht, "Lineare algebra." <http://www.sam.math.ethz.ch/~mhg/unt/LA/HS07/LAS07.pdf>, 2007.